Hartwig's triple reverse order law revisited

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Abstract

We extend the classical Hartwig's triple reverse order law for the Moore-Penrose inverse to closed-range bounded linear operators on infinite dimensional Hilbert spaces.

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1 Introduction

If S is a semigroup with the unit 1, and if $a, b \in S$ are invertible, then the equality $(ab)^{-1} = b^{-1}a^{-1}$ is called the reverse order law for the ordinary inverse. It is well-known that the reverse order law does not hold for various classes of generalized inverses.

In this paper we specialize our investigations to the Moore-Penrose inverse of a triple product of closed range bounded linear operators on Hilbert spaces.

Let X,Y,Z be Hilbert spaces, and let $\mathcal{L}(X,Y)$ denote the set of all bounded linear operators from X to Y. We abbreviate $\mathcal{L}(X) = \mathcal{L}(X,X)$. For $A \in \mathcal{L}(X,Y)$ we denote by $\mathcal{N}(A)$ and $\mathcal{R}(A)$, respectively, the null-space and the range of A. An operator $B \in \mathcal{L}(Y,X)$ is an inner inverse of A, if ABA = A holds. In this case A is inner invertible, or relatively regular. It is well-known that A is inner invertible if and only if $\mathcal{R}(A)$ is closed in Y. The Moore-Penrose inverse of $A \in \mathcal{L}(X,Y)$ is the operator $X \in \mathcal{L}(Y,X)$ which satisfies the Penrose equations

$$AXA = A$$
, $XAX = X$, $(AX)^* = AX$, $(XA)^* = XA$.

The Moore-Penrose inverse of A exists if and only if $\mathcal{R}(A)$ is closed in Y. If the Moore-Penrose inverse of A exists, then it is unique, and it is denoted by A^{\dagger} .

The rule $(AB)^{\dagger} = B^{\dagger}A^{\dagger}$ (in the case when A, B, AB have closed ranges) does not hold in general. The equivalence conditions can be found in [7] for complex matrices; see [8], [2] and [3] for closed range bounded linear

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operators on Hilbert spaces; see [9] for Moore-Penrose invertible elements in rings and C^* -algebras.

Notice that the reverse order rule attracts a significant attention (see [1], [4], [6], [10], [11] and [13]).

The classical result of Hartwig [12] deals with the triple reverse order law of the form

$$(ABC)^{\dagger} = C^{\dagger}B^{\dagger}A^{\dagger},\tag{1}$$

where A, B, C are matrices. Hartwig establishes several equivalent conditions such that (1) holds, offering a very general proof of the main result. However, one implication in [12] is not valid in infinite dimensional Hilbert spaces, and thus we find it interesting to extend Hartwig's proof in this direction.

We start with some auxiliary results.

Lemma 1.1. Let $A \in \mathcal{L}(X,Y)$ have a closed range. Then A has the matrix decomposition with respect to the orthogonal decompositions of spaces $X = \mathcal{R}(A^*) \oplus \mathcal{N}(A)$ and $Y = \mathcal{R}(A) \oplus \mathcal{N}(A^*)$:

$$A = \left[\begin{array}{cc} A_1 & 0 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} \mathcal{R}(A^*) \\ \mathcal{N}(A) \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(A) \\ \mathcal{N}(A^*) \end{array} \right],$$

where A_1 is invertible. Moreover,

$$A^{\dagger} = \left[egin{array}{cc} A_1^{-1} & 0 \ 0 & 0 \end{array}
ight] : \left[egin{array}{cc} \mathcal{R}(A) \ \mathcal{N}(A^*) \end{array}
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ight].$$

The proof of the previous result is straightforward.

Lemma 1.2. [6] Let $A \in \mathcal{L}(X,Y)$ have a closed range. Let X_1 and X_2 be closed and mutually orthogonal subspaces of X, such that $X = X_1 \oplus X_2$. Let Y_1 and Y_2 be closed and mutually orthogonal subspaces of Y, such that $Y = Y_1 \oplus Y_2$. Then the operator A has the following matrix representations with respect to the orthogonal sums of subspaces $X = X_1 \oplus X_2 = \mathcal{R}(A^*) \oplus \mathcal{N}(A)$, and $Y = \mathcal{R}(A) \oplus \mathcal{N}(A^*) = Y_1 \oplus Y_2$:

$$A = \left[\begin{array}{cc} A_1 & A_2 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} X_1 \\ X_2 \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(A) \\ \mathcal{N}(A^*) \end{array} \right],$$

where $D = A_1 A_1^* + A_2 A_2^*$ maps $\mathcal{R}(A)$ into itself and D > 0. Also,

$$A^{\dagger} = \left[\begin{array}{cc} A_1^* D^{-1} & 0 \\ A_2^* D^{-1} & 0 \end{array} \right].$$

(b)
$$A = \begin{bmatrix} A_1 & 0 \\ A_2 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(A^*) \\ \mathcal{N}(A) \end{bmatrix} \to \begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix},$$

where $D = A_1^*A_1 + A_2^*A_2$ maps $\mathcal{R}(A^*)$ into itself and D > 0. Also,

$$A^{\dagger} = \left[\begin{array}{cc} D^{-1}A_1^* & D^{-1}A_2^* \\ 0 & 0 \end{array} \right].$$

Here A_i denotes different operators in any of these two cases.

Lemma 1.3. Let $A \in \mathcal{L}(X,Y)$ be closed range operator and let P_M be orthogonal projection from Y to closed subspace $\mathcal{R}(M) \subset \mathcal{R}(A)$. Then A^*P_MA has a closed range.

Proof. According to Lemma 1.1 and Lemma 1.2, operators A and P_M have the following forms:

$$A = \begin{bmatrix} A_1 & 0 \\ A_2 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(A^*) \\ \mathcal{N}(A) \end{bmatrix} \to \begin{bmatrix} \mathcal{R}(M) \\ \mathcal{N}(M) \end{bmatrix},$$

$$P_M = \left[\begin{array}{cc} I & 0 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} \mathcal{R}(M) \\ \mathcal{N}(M) \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(M) \\ \mathcal{N}(M) \end{array} \right].$$

It is obvious that $A^*P_MA = (P_MA)^*P_MA$, and by using well-known fact that for any bounded linear operator T holds: T^*T has closed range if and only if T has closed range, it is enough to prove that P_MA is closed range operator. From the form of P_MA :

$$P_M A = \left[\begin{array}{cc} I & 0 \\ 0 & 0 \end{array} \right] \left[\begin{array}{cc} A_1 & 0 \\ A_2 & 0 \end{array} \right] = \left[\begin{array}{cc} A_1 & 0 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{cc} \mathcal{R}(A^*) \\ \mathcal{N}(A) \end{array} \right] \to \left[\begin{array}{cc} \mathcal{R}(M) \\ \mathcal{N}(M) \end{array} \right],$$

we have $\mathcal{R}(P_MA) = \mathcal{R}(A_1) = A_1(\mathcal{R}(A^*))$, which is closed because A_1 is onto. Indeed, let us suppose A_1 is not onto; this means there is some $y \in \mathcal{R}(M) \setminus \mathcal{R}(A_1)$. Because of $\mathcal{R}(M) \subset \mathcal{R}(A)$, there is some $x \in \mathcal{R}(A^*)$ such that $y = A_1x + A_2x$, provided that $A_2x \neq 0$. Therefore, $\mathcal{R}(M) \ni y - A_1x = A_2x \in \mathcal{N}(M)$, and sum $\mathcal{R}(M) \oplus \mathcal{N}(M)$ is direct, so $A_2x = 0$, which is contradiction. Therefore, A_1 is onto.

2 Main result

In this section we extend results due to Hartwig [12] concerning the triple reverse order law for the Moore-Penrose inverse from complex matrices to infinite dimensional settings.

In this section, let X_i , i = 1, 2, 3, 4, be arbitrary Hilbert spaces, and let $A \in \mathcal{L}(X_3, X_4)$, $B \in \mathcal{L}(X_2, X_3)$ and $C \in \mathcal{L}(X_1, X_2)$ be bounded linear operators with closed ranges. We use notations in the same way as in [12]:

$$M = ABC,$$
 $X = C^{\dagger}B^{\dagger}A^{\dagger},$ $E = A^{\dagger}A,$ $F = CC^{\dagger},$ $Q = FB^{\dagger}E.$

Recall that $K \in L(X)$ is EP, if K has a closed range, and $KK^{\dagger} = K^{\dagger}K$. The main result is the following theorem.

Theorem 2.1. Let A, B, C be closed-range operators such that ABC also has a closed range. The following statements are equivalent:

- (a) $(ABC)^{\dagger} = C^{\dagger}B^{\dagger}A^{\dagger}$;
- (b) PQP = P, QPQ = Q, and both of A*APQ, and QPCC* are Hermitian:
- (c) PQP = P, QPQ = Q, and both of A^*APQ , and $QPCC^*$ are EP;
- (d) PQP = P, $\mathcal{R}(A^*AP) = \mathcal{R}(Q^*)$, $\mathcal{R}(CC^*P^*) = \mathcal{R}(Q)$;

(e)
$$(PQ)^2 = PQ$$
, $\mathcal{R}(A^*AP) = \mathcal{R}(Q^*)$, $\mathcal{R}(CC^*P^*) = \mathcal{R}(Q)$.

Proof. The proof given by Hartwig stays valid for $(a) \Leftrightarrow (b)$, $(b) \Rightarrow (c)$, $(c) \Rightarrow (d)$ and $(d) \Rightarrow (e)$. The only case which does not hold in general, is actually the implication $(e) \Rightarrow (b)$, which involves properties of the matrix rank. Thus, this part of the proof is not applicable to operators on infinite dimensional Hilbert space.

To complete the proof, we will prove $(e) \Rightarrow (a)$ in a different way, using properties of operator matrices.

Using Lemma 1.1 we conclude that the operator C has the following matrix form:

$$C = \left[\begin{array}{cc} C_1 & 0 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} \mathcal{R}(C^*) \\ \mathcal{N}(C) \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(C) \\ \mathcal{N}(C^*) \end{array} \right],$$

where C_1 is invertible. Then

$$C^{\dagger} = \left[\begin{array}{cc} C_1^{-1} & 0 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} \mathcal{R}(C) \\ \mathcal{N}(C^*) \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(C^*) \\ \mathcal{N}(C) \end{array} \right].$$

From Lemma 1.2 it follows that the operator B has the following matrix form:

 $B = \left[\begin{array}{cc} B_1 & B_2 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} \mathcal{R}(C) \\ \mathcal{N}(C^*) \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(B) \\ \mathcal{N}(B^*) \end{array} \right],$

where $G = B_1 B_1^* + B_2 B_2^*$ is invertible and positive in $\mathcal{L}(\mathcal{R}(B))$. Then

$$B^{\dagger} = \left[\begin{array}{cc} B_1^* G^{-1} & 0 \\ B_2^* G^{-1} & 0 \end{array} \right].$$

From Lemma 1.2 it also follows that the operator A has the following matrix form:

$$A = \left[\begin{array}{cc} A_1 & A_2 \\ 0 & 0 \end{array} \right] : \left[\begin{array}{c} \mathcal{R}(B) \\ \mathcal{N}(B^*) \end{array} \right] \to \left[\begin{array}{c} \mathcal{R}(A) \\ \mathcal{N}(A^*) \end{array} \right],$$

where $D = A_1 A_1^* + A_2 A_2^*$ is invertible and positive in $\mathcal{L}(\mathcal{R}(A))$. Then

$$A^{\dagger} = \left[\begin{array}{cc} A_1^* D^{-1} & 0 \\ A_2^* D^{-1} & 0 \end{array} \right].$$

Let us find the expressions for the operators M, X, E, F, P and Q. It is easy to find that:

$$M = ABC = \begin{bmatrix} A_1 B_1 C_1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} M_1 & 0 \\ 0 & 0 \end{bmatrix}, \quad M_1 = A_1 B_1 C_1;$$

$$X = C^{\dagger} B^{\dagger} A^{\dagger} = \begin{bmatrix} C_1^{-1} B_1^* G^{-1} A_1^* D^{-1} & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} X_1 & 0 \\ 0 & 0 \end{bmatrix},$$

$$X_1 = C_1^{-1} B_1^* G^{-1} A_1^* D^{-1};$$

$$E = A^{\dagger}A = \left[\begin{array}{cc} A_1^*D^{-1}A_1 & A_1^*D^{-1}A_2 \\ A_2^*D^{-1}A_1 & A_2^*D^{-1}A_2 \end{array} \right]; \quad F = CC^{\dagger} = \left[\begin{array}{cc} I & 0 \\ 0 & 0 \end{array} \right];$$

$$P = EBF = \begin{bmatrix} A_1^* D^{-1} A_1 B_1 & 0 \\ A_2^* D^{-1} A_1 B_1 & 0 \end{bmatrix} = \begin{bmatrix} A_1^* D^{-1} M_1 C_1^{-1} & 0 \\ A_2^* D^{-1} M_1 C_1^{-1} & 0 \end{bmatrix};$$

$$Q = FB^{\dagger}E = \begin{bmatrix} B_1^*G^{-1}A_1^*D^{-1}A_1 & B_1^*G^{-1}A_1^*D^{-1}A_2 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} C_1X_1A_1 & C_1X_1A_2 \\ 0 & 0 \end{bmatrix}.$$

It will be convinient to compute here matrix forms for some expressions appearing in the rest of the proof:

$$PQ = \begin{bmatrix} A_1^*D^{-1}M_1X_1A_1 & A_1^*D^{-1}M_1X_1A_2 \\ A_2^*D^{-1}M_1X_1A_1 & A_2^*D^{-1}M_1X_1A_2 \end{bmatrix};$$

$$QP = \begin{bmatrix} C_1X_1M_1C_1^{-1} & 0 \\ 0 & 0 \end{bmatrix};$$

$$A^*AP = \begin{bmatrix} A_1^*M_1C_1^{-1} & 0 \\ A_2^*M_1C_1^{-1} & 0 \end{bmatrix};$$

$$CC^*P^* = \begin{bmatrix} C_1M_1^*D^{-1}A_1 & C_1M_1^*D^{-1}A_2 \\ 0 & 0 \end{bmatrix};$$

$$(PQ)^2 = \begin{bmatrix} A_1^*D^{-1}M_1X_1M_1X_1A_1 & A_1^*D^{-1}M_1X_1M_1X_1A_2 \\ A_2^*D^{-1}M_1X_1M_1X_1A_1 & A_2^*D^{-1}M_1X_1M_1X_1A_2 \end{bmatrix}.$$

Now, we will find equivalent expressions for the conditions (a) and (e) in the terms of the components of the operators A, B and C.

(a): This is equivalent to
$$(A_1B_1C_1)^{\dagger} = C_1^{-1}B_1^*G^{-1}A_1^*D^{-1}$$
, or $M_1^{\dagger} = X_1$.

(e): This is equivalent to the following three expressions:

$$(e.1) \ \Leftrightarrow \ A_i^*D^{-1}(M_1X_1)^2A_j = A_i^*D^{-1}M_1X_1A_j, \quad \text{ for all } i,j \in \{1,2\};$$

$$(e.2) \Leftrightarrow \mathcal{R}\left(\left[\begin{array}{cc} A_1^*M_1C_1^{-1} & 0\\ A_2^*M_1C_1^{-1} & 0 \end{array}\right]\right) = \mathcal{R}\left(\left[\begin{array}{cc} A_1^*X_1^*C_1^* & 0\\ A_2^*X_1^*C_1^* & 0 \end{array}\right]\right);$$

$$(e.3) \hspace{0.2cm} \Leftrightarrow \hspace{0.2cm} \mathcal{R}\left(\left[\begin{array}{ccc} C_1M_1^*D^{-1}A_1 & C_1M_1^*D^{-1}A_2 \\ 0 & 0 \end{array}\right]\right) = \mathcal{R}\left(\left[\begin{array}{ccc} C_1X_1A_1 & C_1X_1A_2 \\ 0 & 0 \end{array}\right]\right).$$

Recall that we prove the implication (e) \Longrightarrow (a).

Now, if we premultiply (e.1) by A_i , and use summation over i = 1, 2 we yield $(M_1X_1)^2A_j = M_1X_1A_j$, for j = 1, 2. If we now postmultiply last expression by A_j^* and add them, we have $(M_1X_1)^2 = M_1X_1$. Therefore:

$$(e.1) \implies (M_1 X_1)^2 = M_1 X_1. \tag{2}$$

On the other hand, (e.2) is equivalent to:

$$\mathcal{R}(A_i^* M_1 C_1^{-1}) = \mathcal{R}(A_i^* X_1^* C_1^*), \quad i = 1, 2.$$

Again, if A_i acts on both sides, and we add them, we obtain:

$$\mathcal{R}(M_1C_1^{-1}) = \mathcal{R}(X_1^*C_1^*).$$

Hence, we have

$$\mathcal{R}(M_1) = \mathcal{R}(X_1^*),$$

which implies $M_1 M_1^{\dagger} = X_1^{\dagger} X_1$. Therefore,

$$(e.2) \Rightarrow M_1 M_1^{\dagger} = X_1^{\dagger} X_1.$$

Let us now write (e.3) as:

$$\mathcal{N}\left(\left[\begin{array}{cc} A_1^*D^{-1}M_1C_1^* & 0\\ A_2^*D^{-1}M_1C_1^* & 0 \end{array}\right]\right) = \mathcal{N}\left(\left[\begin{array}{cc} A_1^*X_1^*C_1^* & 0\\ A_2^*X_1^*C_1^* & 0 \end{array}\right]\right).$$

Notice that

$$\mathcal{N}\left(\left[\begin{array}{cc}A_1^*D^{-1}M_1C_1^* & 0\\A_2^*D^{-1}M_1C_1^* & 0\end{array}\right]\right) = \left\{\left[\begin{array}{c}u_1\\u_2\end{array}\right] : \left[\begin{array}{cc}A_1^*D^{-1}M_1C_1^* & 0\\A_2^*D^{-1}M_1C_1^* & 0\end{array}\right] \left[\begin{array}{c}u_1\\u_2\end{array}\right] = \left[\begin{array}{c}0\\0\end{array}\right]\right\},$$

and we conclude:

$$\mathcal{N}\left(\left[\begin{array}{cc} A_1^*D^{-1}M_1C_1^* & 0\\ A_2^*D^{-1}M_1C_1^* & 0 \end{array}\right]\right) = \left(\mathcal{N}(A_1^*D^{-1}M_1C_1^*)\cap \mathcal{N}(A_2^*D^{-1}M_1C_1^*)\right) \oplus \mathcal{N}(C^*),$$

which is further equal (easy to see) to

$$\mathcal{N}(M_1C_1^*) \oplus \mathcal{N}(C^*).$$

With a little effort we find

$$\mathcal{N}\left(\left[\begin{array}{cc} A_1^*X_1^*C_1^* & 0 \\ A_2^*X_1^*C_1^* & 0 \end{array}\right]\right) = \left(\mathcal{N}(A_1^*X_1^*C_1^*) \cap \mathcal{N}(A_2^*X_1^*C_1^*)\right) \oplus \mathcal{N}(C^*) = \\ = \mathcal{N}(X_1^*C_1^*) \oplus \mathcal{N}(C^*).$$

Hence, the condition (e.3) implies:

$$\mathcal{N}(M_1C_1^*) = \mathcal{N}(X_1^*C_1^*),$$

which is the same as $\mathcal{R}(C_1M_1^*) = \mathcal{R}(C_1X_1)$, or $\mathcal{R}(M_1^*) = \mathcal{R}(X_1)$, or even

further: $M_1^{\dagger}M_1 = X_1X_1^{\dagger}$. Since we intend to prove $(e) \Rightarrow (a)$, it is enough to prove the following

$$((M_1X_1)^2 = M_1X_1, \quad M_1M_1^{\dagger} = X_1^{\dagger}X_1, \quad M_1^{\dagger}M_1 = X_1X_1^{\dagger}) \Rightarrow M_1^{\dagger} = X_1.$$

The following completes the proof:

$$\begin{split} M_1 &= M_1 X_1 X_1^\dagger = M_1 X_1 X_1^\dagger X_1 X_1^\dagger = M_1 X_1 M_1 M_1^\dagger X_1^\dagger = \\ &= M_1 X_1 M_1 X_1 X_1^\dagger M_1^\dagger X_1^\dagger = M_1 X_1 X_1^\dagger M_1^\dagger X_1^\dagger = \\ &= M_1 M_1^\dagger X_1^\dagger = X_1^\dagger X_1 X_1^\dagger = X_1^\dagger. \end{split}$$

For the sake of completeness, we remark that operators A^*APQ and $QPCC^*$ from part (c) of our Theorem have closed ranges. It immediately follows from Lemma 1.3 because:

$$A^*APQ = A^*MM^{\dagger}A = A^*P_{\mathcal{R}(M)}A, \ QPCC^* = CM^{\dagger}MC^* = CP_{\mathcal{R}(M)}C^*.$$

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